

ΦΥΣΙΚΗ Γ' ΛΥΚΕΙΟΥ ΘΕΤΙΚΗΣ ΚΑΤΕΥΘΥΝΣΗΣ

ΑΠΑΝΤΗΣΕΙΣ

ΘΕΜΑ Α

A₁) → Γ, A₂) → Β, A₃) → Β, A₄) → Β

A₅) $\begin{cases} A \rightarrow \text{Λάθος} \\ B \rightarrow \text{Σωστό} \\ \Gamma \rightarrow \text{Σωστό} \\ \Delta \rightarrow \text{Λάθος} \\ E \rightarrow \text{Σωστό} \end{cases}$

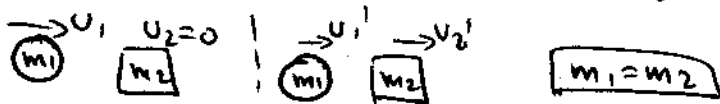
ΘΕΜΑ Β1 Σωστό είναι το (γ)

$$E_1 = E_2 \Rightarrow \frac{1}{2} D A_1^2 = \frac{1}{2} D A_2^2 \Rightarrow \boxed{A_1 = A_2}$$

$$E_{\text{ολ}} = E_1 \Rightarrow \frac{1}{2} D A_{\text{ολ}}^2 = \frac{1}{2} D A_1^2 \Rightarrow \boxed{A_{\text{ολ}} = A_1}$$

$$A_{\text{ολ}} = \sqrt{A_1^2 + A_2^2 + 2A_1 A_2 \cos \varphi} \Rightarrow A_1^2 = A_1^2 + A_1^2 + 2A_1 A_1 \cos \varphi \Rightarrow \cos \varphi = -\frac{1}{2} \Rightarrow \varphi = \frac{2\pi}{3}$$

ΘΕΜΑ Β2 Σωστό είναι το (α)



$$u_2' = 36\% u_1 \Rightarrow \frac{1}{2} m_2 u_2'^2 = \frac{36}{100} \frac{1}{2} m_1 u_1^2 \Rightarrow \boxed{u_2' = 0,6 u_1}$$

$$A_{\text{ολ}} \Rightarrow m_1 u_1 = m_1 u_1' + m_2 u_2' \Rightarrow \boxed{u_2' = 0,4 u_1}$$

$$K_{\text{ολ}} = \frac{1}{2} m_1 u_1'^2 + \frac{1}{2} m_2 u_2'^2 = \frac{1}{2} m_1 (0,36 u_1^2 + 0,16 u_1^2) = 0,52 \cdot \frac{1}{2} m_1 u_1^2 = 0,52 K_1$$

$$Q_{\text{αα}} = K_{\text{ολ}} - K_{\text{αγ}} = K_1 - 0,52 K_1 = 0,48 K_1$$

Θέμα Β3 Σωστό το (ii)

$$f_{\Delta} = \frac{1}{T_{\Delta}} = \frac{1}{0,7 - 0,2} = \frac{1}{0,5} \Rightarrow \boxed{f_{\Delta} = 2 \text{ Hz}} \quad f_2 - f_1 = f_{\Delta} \Rightarrow \boxed{f_2 = 21 \text{ Hz}}$$

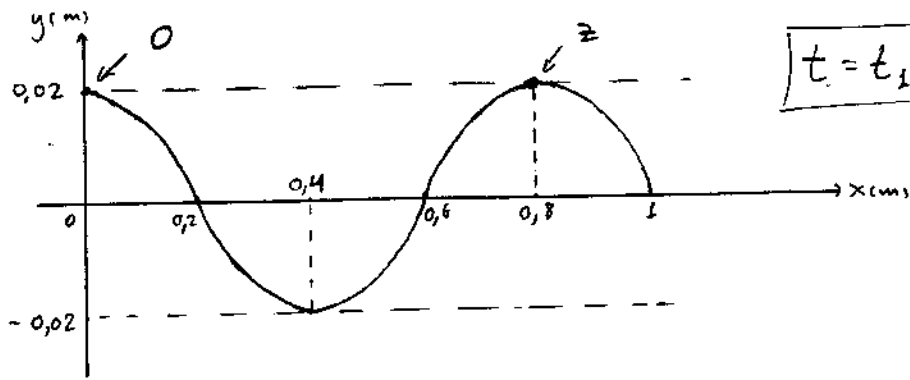
$$f_{\text{αλ}} = \frac{f_1 + f_2}{2} \Rightarrow \boxed{f_{\text{αλ}} = 20 \text{ Hz}}$$

Θέμα Β4 Σωστό το (.)

$$K_{\text{κέντρ}} = K_{\text{ακέρ}} \Rightarrow \frac{1}{2} m \cdot u_{\text{κέν}}^2 = \frac{1}{2} I \omega^2 \quad \underline{u_{\text{κέν}} = \omega R} \Rightarrow m \omega^2 R^2 = I \omega^2$$

$$\Rightarrow I = m R^2 \Rightarrow \text{Δαυρώσιος}$$

ΘΕΜΑ Γ'



$t = t_1$

Γ1) $y = 2A \sin\left(\frac{2\pi x}{\lambda}\right) \cos\left(\frac{2\pi t}{T}\right)$
 $y = 0,02 \sin\left(\frac{2\pi x}{0,8}\right) \cos\left(\frac{2\pi t}{0,4}\right)$
 $y = 0,02 \sin(2,5\pi x) \cos(5\pi t) \quad (s.i)$

Σχήμα : $2A = 0,02 \text{ m}$
 $\lambda = 0,8 \text{ m}$

λοχύει $\Delta t = \frac{T}{4} \Rightarrow 0,1 = \frac{T}{4} \Rightarrow T = 0,4 \text{ se}$

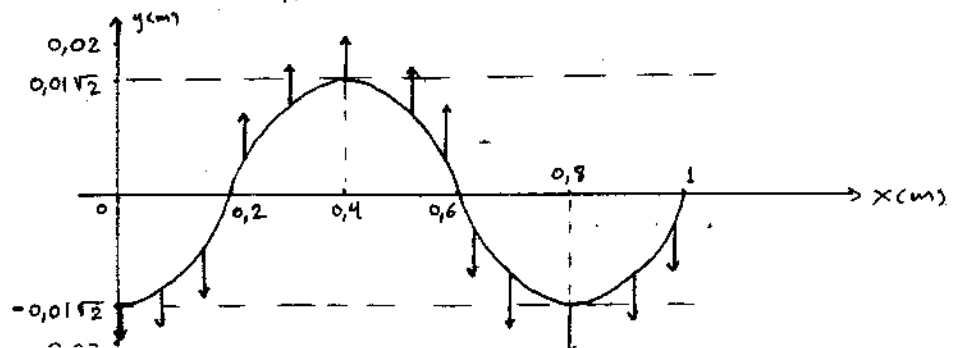
Γ2) $v_z = \dot{y} = \dot{\omega} \cdot 2A \sin(2,5\pi x_z) \cos(5\pi t)$
 $v_z = 5\pi \cdot 0,02 \sin(2,5\pi \cdot 0,8) \cos(5\pi \cdot 1,05)$
 $v_z = 0,1\pi \cdot \underbrace{\sin(2\pi)}_1 \cos(5,25\pi)$
 $v_z = 0,1\pi \sin\left(4\pi + \frac{5\pi}{4}\right)$
 $v_z = 0,1\pi \sin\left(\pi + \frac{\pi}{4}\right)$
 $v_z = -0,1\pi \sin\left(\frac{\pi}{4}\right) \Rightarrow v_z = -0,1\pi \frac{\sqrt{2}}{2} \Rightarrow v_z = -0,05\sqrt{2} \pi \text{ m/s}$

$\omega = \frac{2\pi}{T}$
 $\omega = \frac{2\pi}{0,4}$
 $\omega = 5\pi \text{ rad/s}$

Γ3) $y_0 = 0,02 \cdot \sin(2,5\pi x_0) \cdot \cos(5\pi \cdot 1,05)$
 $y_0 = 0,02 \cdot \underbrace{\sin(2,5\pi \cdot 0)}_1 \cos(5,25\pi)$

$y_0 = 0,02 \cos\left(\pi + \frac{\pi}{4}\right) \Rightarrow y_0 = -0,02 \cos\left(\frac{\pi}{4}\right) \Rightarrow y_0 = -0,02 \frac{\sqrt{2}}{2} \Rightarrow y_0 = -0,01\sqrt{2} \text{ m}$

Επειδή μεταξύ 0,2 περιλαμβάνονται 2 δεσμοί τα σημεία αυτά έχουν ίδια φορά κίνησης, άρα των $t_2 = 1,05 \text{ sec}$ λοχύει $v_0 < 0$



Γ4) Αρχικά: $x_2 = \lambda$

Τελικά: $x_2 = (2N+1) \frac{\lambda'}{4} \xrightarrow{(2: \text{δίσταση διαφ.})} \xrightarrow{(N=1)} x_2 = \frac{3\lambda'}{4}$

=>

=> $\lambda = \frac{3}{4} \lambda' \Rightarrow \frac{v_{\text{κιν}}}{f} = \frac{3}{4} \frac{v_{\text{κιν}}}{f'}$

$f = \frac{1}{T}$

$f = \frac{1}{0,4}$

$f = 2,5 \text{ Hz}$

=> $f' = \frac{3}{4} f \Rightarrow f' = \frac{3}{4} \cdot \frac{5}{2} \Rightarrow f' = \frac{15}{8} \text{ Hz}$

άρα $\Delta f = f' - f \Rightarrow \Delta f = \frac{15}{8} - \frac{5}{2} \Rightarrow \Delta f = \frac{15}{8} - \frac{20}{8}$

=> $\Delta f = -\frac{5}{8} \Rightarrow \Delta f = -0,625 \text{ Hz}$

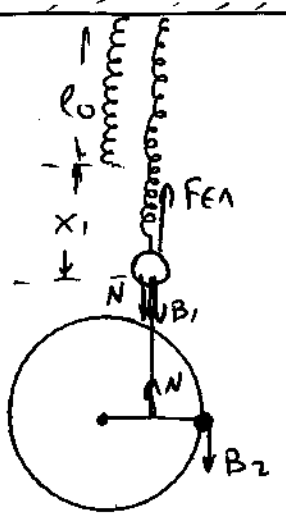
ΘΕΜΑ Δ

Α) $\sum \tau = 0 \Rightarrow m_2 g R - N \frac{R}{2} = 0 \Rightarrow N = 2m_2 g \Rightarrow N = 2N_1$

$\sum F = 0 \Rightarrow F_{\text{ελ}} = N + B_1 \Rightarrow k \cdot x_1 = N + m_1 g \Rightarrow$

$\Rightarrow x_1 = 0,3 \text{ m}$

$U_{\text{ελ}} = \frac{1}{2} k x_1^2 \Rightarrow U_{\text{ελ}} = 0,45 \text{ J}$



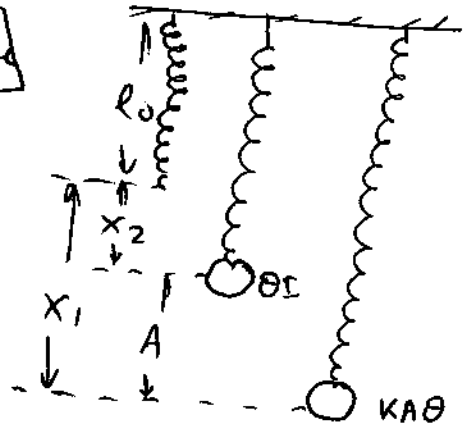
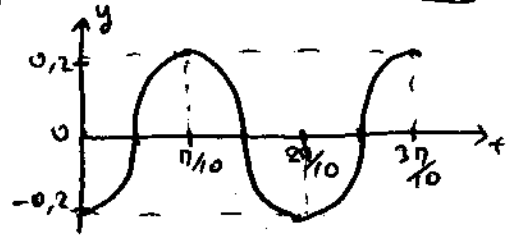
Β1) $\theta \uparrow \Rightarrow \sum f = 0 \Rightarrow m_1 g = k x_2 \Rightarrow x_2 = 0,1 \text{ m}$

$A = x_1 - x_2 \Rightarrow A = 0,2 \text{ m}$ $T = 2\pi \sqrt{\frac{m_1}{k}} \Rightarrow T = \frac{2\pi}{10} \text{ sec}$

$\omega = \frac{2\pi}{T} \Rightarrow \omega = 10 \text{ rad/s}$

$y = A \sin(\omega t + \phi_0) \xrightarrow[t_0=0]{y=-A} \sin \phi_0 = -1 \Rightarrow \phi_0 = \frac{3\pi}{2}$

$y = 0,2 \sin(10t + \frac{3\pi}{2})$



ΔB_2) Το σώμα αρχικά θα κινηθεί προς τα πάνω οωδτε θα ξεπεράσει αδό τη θέση 2^η φορά όταν θα μεταβαίει οωδτε η ταχύτητα U θα είναι αρνητική.

$$U^2 = \omega^2 (A^2 - x^2) \Rightarrow U = \pm \omega \sqrt{A^2 - x^2} \xrightarrow{U < 0} U = -\sqrt{3} \text{ m/s}$$

$$\frac{dP}{dt} = \sum F = F_{en} = -DX_2 = -k \cdot x_2 \Rightarrow \frac{dP}{dt} = -10 \text{ N}$$

$$\frac{dK}{dt} = \sum F \cdot U = -k \cdot x_2 \cdot U \Rightarrow \frac{dK}{dt} = \sqrt{3} \text{ J/s}$$

$$\Delta B_3) I_{01} = I_{\Delta 1EK} + I_{m_2} = \frac{1}{2} MR^2 + m_2 R^2 \Rightarrow I_{01} = 0,25 \text{ kgm}^2$$

$$\sum \tau = I_{01} \cdot \alpha_{\omega} \Rightarrow m_2 g R = I_{01} \cdot \frac{d\omega}{dt} \Rightarrow \frac{d\omega}{dt} = \frac{m_2 g R}{I_{01}}$$

$$\Rightarrow \frac{d\omega}{dt} = 2 \text{ rad/s}^2$$

$$\Delta B_4) \Delta M E \Rightarrow U_{dex}^{Bap} + K_{dex}^{ορ} = U_{TE1}^{Bap} + K_{TE1}^{ορ}$$

$$\Rightarrow m_2 g R + 0 = 0 + \frac{1}{2} I_{01} \omega^2 \Rightarrow$$

$$\omega = \sqrt{\frac{2 \cdot m_2 \cdot g \cdot R}{I_{01}}} = \sqrt{4} \Rightarrow \omega = 2 \text{ rad/s}$$

$$L = I_{01} \omega \Rightarrow L = 0,5 \text{ kg} \frac{\text{m}^2}{\text{s}^2}$$

